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to provide a coherent way of dealing with the tuning of PID controllers. The particular method at the core of the book is the so-called model-reference robust tuning (MoReRT), developed by the authors. MoReRT constitutes a novel and powerful way of thinking of a robust design and taking into account the usual design trade-offs encountered

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As shown in [1], controller tuning rules may be classified using different criteria: based on the controlled process information used (model order and structure, critical information), on the control algorithm to tune (P, PD, PI, PID, one or two-degree-of freedom), and on the controller design criteria (performance, robustness, or a combination of both) using analytical or optimization procedures.

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