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papers accepted for presentation and discussion at ROBOT 2015: Second Iberian Robotics Conference, held in Lisbon, Portugal, November 19th-21th, 2015. ROBOT 2015 is part of a series of conferences that are a joint organization of SPR – “ Sociedade Portuguesa de Rob ó tica/ Portuguese Society for Robotics ” , SEIDROB – Sociedad Española para la Investigaci ó n y Desarrollo de la Rob ó tica/ Spanish Society for Research and Development in Robotics and CEA-GTRob – Grupo Tem á tico de Rob ó tica/ Robotics Thematic Group. The conference organization had also the collaboration of several universities and research institutes, including: University of

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Minho, University of Porto, University of Lisbon, Polytechnic Institute of Porto, University of Aveiro, University of Zaragoza, University of Malaga, LIACC, INESC-TEC and LARSyS. Robot 2015 was focussed on the Robotics scientific and technological activities in the Iberian Peninsula, although open to research and delegates from other countries. The conference featured 19 special sessions, plus a main/general robotics track. The special sessions were about: Agricultural Robotics and Field Automation; Autonomous Driving and Driver Assistance Systems; Communication Aware Robotics; Environmental Robotics; Social Robotics: Intelligent and Adaptable AAL Systems; Future Industrial



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Explains the basic principles of construction and operation of industrial robots, the tasks that they can perform in the manufacturing industry, and the

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measures necessary for their safe and economic installation and operation. The second edition (first in 1990) includes new examples of flowcharting and programming, recent applications in the automobile industry, and a glossary without pronunciation. For graduate or undergraduate students of robotics and automation systems. Annotation copyright by Book News, Inc., Portland, OR

"While many scholarly writings have just echoed practical management problems, this volume broadens the approach to projects. First, the contributions made expand the scope from single projects to projects in their corporate and social contexts.

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This book features selected papers presented at the 14th International Conference on Electromechanics and Robotics ' Zavalishin ' s Readings ' – ER(ZR) 2019, held in Kursk, Russia, on April 17 – 20, 2019. The contributions, written by professionals, researchers and students, cover topics in the field of automatic control systems, electromechanics, electric power engineering and electrical engineering, mechatronics, robotics, automation and vibration

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technologies. The Zavalishin's Readings conference was established as a tribute to the memory of Dmitry Aleksandrovich Zavalishin (1900 – 1968) – a Russian scientist, corresponding member of the USSR Academy of Sciences, and founder of the school of valve energy converters based on electric machines and valve converters energy. The first conference was organized by the Institute of Innovative Technologies in Electromechanics and Robotics at the Saint Petersburg State University of Aerospace Instrumentation in 2006. The 2019 conference was held with the XIII International Scientific and Technical Conference “ Vibration 2019 ” , and was organized by Saint Petersburg

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State University of Aerospace Instrumentation (SUAI), Saint Petersburg Institute for Informatics and Automation of the Russian Academy of Sciences (SPIIRAS) and the Southwest State University (SWSU) in with cooperation Russian Foundation for Basic Research (project No. 19-08-20021).

Successful innovation is a true challenge and especially when today ' s companies are intertwined in close inter-organisational relationships and networks with e.g. customers and suppliers. Research has indicated that accounting can play important roles in such innovation processes,

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but there is little in-depth systematic knowledge about this issue. Accounting, Innovation and Inter-Organisational Relationships gathers leading researchers from all around the world to argue for the importance of more systematic knowledge about accounting, innovation and inter-organisational relationships. Accounting, Innovation and Inter-Organisational Relationships thus becomes an important source for researchers and practitioners interested in accounting and inter-organisational relationships as well as the related disciplines of management, marketing, innovation and strategy.

This book highlights recent

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findings in industrial, manufacturing and mechanical engineering, and provides an overview of the state of the art in these fields, mainly in Russia and Eastern Europe. A broad range of topics and issues in modern engineering are discussed, including the dynamics of machines and working processes, friction, wear and lubrication in machines, surface transport and technological machines, manufacturing engineering of industrial facilities, materials engineering, metallurgy, control systems and their industrial applications, industrial mechatronics, automation and robotics. The book gathers selected papers presented at the 6th International Conference on

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Industrial Engineering (ICIE), held in Sochi, Russia in May 2020. The authors are experts in various fields of engineering, and all papers have been carefully reviewed. Given its scope, the book will be of interest to a wide readership, including mechanical and production engineers, lecturers in engineering disciplines, and engineering graduates.

Robot Modeling and Kinematics teaches the fundamental topics of robotics, using cutting-edge visualization software and computer tools to illustrate topics and provide a comprehensive process of teaching and learning.



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The book provides an introduction to robotics with an emphasis on the study of robotic arms, their mathematical description, and the equations describing their motion. It teaches how to model robotic arms efficiently and analyze their kinematics. The kinematics of robot manipulators is also presented beginning with the use of simple robot mechanisms and progressing to the most complex robot manipulator structures.

While mathematically rigorous, the book's focus is on ease of understanding of the concepts with interactive animated computer graphics illustrations and modeling software that allow clear understanding of the material covered in the book. All necessary computations are concisely

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explained and software is provided that greatly eases the computational burden normally associated with robotics. Written for use in a robotics course or as a professional reference, Robot Modeling and Kinematics is an essential resource that provides a thorough understanding of the topics of modeling and kinematics.

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